# POWER MOLLER'YY! 

We thank you for your purchase of our Power Moller or Motorised drum.
Please read this handling instructions first to understand the product, safety information and cautions before using the product.
Keep this handling instructions readily accessible for reference.
Applicable models: PM486XE/XP, PM500XE/XP, PM570XE/XP, PM605XE/XP

## After opening the package

Make sure whether the product you received complies to your purchase order, with its designation, specifications and operating voltage.


## Dimensions



- M8 Connector cable
- D-shaped shaft



## Mounting bracket (option)

No.A-A80-G (with I/O terminal)


No. 313

In this handling instructions, safety instructions are classified into "Danger" and "Warning" as per below description, to ensure the proper use of the product.

| ! WARNING | Failure to comply with instruction may cause death or serious injury. |
| :--- | :--- |
| ! CAUTION | Failure to comply with instruction may cause injury, disability or physical damage. |

## Installation / Wiring

## . WARNING

- Make sure the operating voltage and wiring diagrame to ensure the correct wiring, to avoid electrical shock and fire.
- Respect the procedure and make sure the connection and wiring for the product.
- Do not use the product in explosive, ignitable gas, corrosive, watery environment, or around flammable products.
- Switch off the power, when conveyor removal, wiring or maintenance is done, otherwise you have a risk of electrical shock or injury.
- Respect the electrical regulations of the site or the equipment, where the product is installed. (Labour safety and sanitary regulations, electrical equipment technical standard, etc)
$\triangle$ CAUTION
- Make sure the Power Moller is tightly fixed in place before operation, ( Use the proper fixing bracket we specify)to avoid injury or damage to the equipment.
- Make sure the rotating direction of the Power Moller before installation to the conveyor frame, to avoid injury or damage to the equipment.
- Make sure not to damage a cable sheath when it goes through the conveyor frame.
- Make sure the Power Moller and fixing bracket is properly fixed in the frame at our specified fastening torque.
- Mount leaving about $2-5 \mathrm{~mm}$ between the Powe Moller and the flame.
- Adjust the horizontal level of the Power Moller and adjacent idler rollers so that the load will be applied evenly to each rollers.
- Make sure the conveyor frame is grounded.
- A device should be set up so that all of Power Moller starting are monitered from the operation position.
- Do not pull (force $>1 \mathrm{~N}$ ), damage, twist, modify, or forcibly bend the power cable or leadwires. Do not stack, put heavy load on the power cable or sandwich it. There will cause serious electric hazard, fire or motor failure.
- This XE/XP series Power Moller is integral motor driver type. Do not give strong impact load to the Power Moller such as drop, strike, so as not to damage the unit.


## Operation

. WARNING

- Do not operate the product with "live" electrical part exposed to avoid electric hazard.
- Turn the RUN/STOP switch to STOP in case of electricity failure, to avoid the risk of injury by the possible sudden restart .
- For accident avoidance, the only person designated by the employer with the training on the operation and maintenance method is allowed to operate.
- The failure of the driver card can make the input/output ON or OFF.

In the place where the accident could happen the monitoring control equipment should be set up outside so as to respond immediately.
$\triangle$ CAUTION

- Do not use for beyond the capacity pf the Power Moller to avoid electrical shock, injury, fire, or damage to the equipment.
- Do not ride on the conveyor where Power Moller is installed, to avoid injury or damage to the equipment.
- At the time of the startup, please confirm the safety and make sure that nobody touches the Power Moller.
- Please an emergency stop button before starting the operation, to avoid injury or damage to the equipment.
- Switch off the power immediately if abnormal situation arises, to avoid electrical shock, injury, or fire,
- Keep your hand or body away from the Power Moller no matter how the unit is powered or unpowered, to avoid a risk of finger trap or heat injury,
- Keep clean around the Power Moller. The packing materials twining around the Power Moller causes the unexpected accident.
- Make sure to load homogeneously. (There is a risk that the power moller get broken and its product lifetime decreases.
- Never start up and shut down the power moller with PS. (There is a risk that the power moller get broken and its product lifetime decrease.
- Do not switch on/off the relay or the contactor. It makes the loud noise to cause the machine blunder.
- The input signal should last longer than 15 ms . Otherwise no reaction or the machine malfunction is caused.
- After power-on Power Moller won't start for a second.


## Transport

## $\triangle$ CAUTION

- Do not hang the product from the power cable, or motor shaft when carrying the product, to avoid injury caused by dropping the product or electrical shock by disconnection.


## Other

## $\triangle$ CAUTION

- Do not disassemble, repair not modify the product (for which we do not warrant). It might be the cause of electrical shock, injury or fire.
- Make sure rent out or transfer of this product should be accompanied by this manual.
- Dispose this product in industrial waste.
- At the time of the maintenance, make sure the main power is switched off prohibiting the machine to operate.


## Power supply

The power supply should not be affected by peak current 20A for 1 msec .


## Wiring

<In case I/O Terminal Bracket (No.A-A80-G/ No.A-A00-G) is not used >

## NPN input


※ Speed variation
Varying external voltage input can also vary the motor speed instead of external resistor. (see page 4)

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<Dripproof option/M85P connector cable>


## Operation

## RUN/STOP

- Power Moller will run and stop by RUN/STOP signal.
- When motor is locked, motor output goes slowly down and runs at intermittent operation. (Error output is not discharged.)


## Motor lock

RUN SIGNAL


Motor $\qquad$
RUN


Rotation direction
. Switch the rotation direction by DIR signal.

- DIR signal can be permitted while motor is running



## Speed variation

- Speed of the Power Moller can be varied either by adjustment of external resistor or by external voltage input.


## PM486XE/XP

| Speed <br> Level | ※External <br> Voltage | ※External <br> Resistor $(\Omega)$ | Nominal <br> Speed <br> 00m/min | Nominal <br> Speed <br> $60 \mathrm{~m} / \mathrm{min}$ | Nominal <br> Speed <br> $30 \mathrm{~m} / \mathrm{min}$ | Nominal <br> Speed <br> $17 \mathrm{~m} / \mathrm{min}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10 | $9.3 \sim 10$ <br> or No input <br> voltage | 9.1 K or over <br> or <br> Open | 101.1 | 60 | 28.4 | 16.9 |
| 9 | $8.5 \pm 0.2$ | 6.2 K | 92.7 | 55 | 26.0 | 15.5 |
| 8 | $7.5 \pm 0.2$ | 4.3 K | 75.8 | 45 | 21.3 | 12.7 |
| 7 | $6.5 \pm 0.2$ | 3.3 K | 67.4 | 40 | 18.9 | 11.3 |
| 6 | $5.5 \pm 0.2$ | 2.2 K | 59.0 | 35 | 16.6 | 9.9 |
| 5 | $4.5 \pm 0.2$ | 1.8 K | 50.6 | 30 | 14.2 | 8.4 |
| 4 | $3.5 \pm 0.2$ | 1.2 K | 33.7 | 20 | 9.5 | 5.6 |
| 3 | $2.5 \pm 0.2$ | 750 | 25.3 | 15 | 7.1 | 4.2 |
| 2 | $1.5 \pm 0.2$ | 430 | 16.9 | 10 | 4.7 | 2.8 |
| 1 | $0 \sim 0.9$ | 120 or less <br> of <br> Short | 12.6 | 7.5 | 3.6 | 2.1 |

※ When the mounting bracket with I/O terminal is mounted, adjust at a pot on the drive card.
PM570XE/XP

| Speed <br> Level | ※External <br> Voltage | *External <br> Resistor $(\Omega)$ | Nominal <br> Speed <br> $100 \mathrm{~m} / \mathrm{min}$ | Nominal <br> Speed <br> $60 \mathrm{~m} / \mathrm{min}$ | Nominal <br> Speed <br> pom/min | Nominal <br> Speed <br> $17 \mathrm{~m} / \mathrm{min}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10 | $9.3 \sim 10$ <br> or <br> oo input <br> voltage | 9.1 K or over <br> or <br> open | 118.6 | 70.4 | 33.3 | 19.8 |
| 9 | $8.5 \pm 0.2$ | 6.2 K | 108.7 | 64.5 | 30.5 | 18.2 |
| 8 | $7.5 \pm 0.2$ | 4.3 K | 88.9 | 52.8 | 25.0 | 14.9 |
| 7 | $6.5 \pm 0.2$ | 3.3 K | 79.1 | 46.9 | 22.2 | 13.2 |
| 6 | $5.5 \pm 0.2$ | 2.2 K | 69.2 | 41.0 | 19.5 | 11.6 |
| 5 | $4.5 \pm 0.2$ | 1.8 K | 59.3 | 35.2 | 16.7 | 9.9 |
| 4 | $3.5 \pm 0.2$ | 1.2 K | 39.5 | 23.5 | 11.1 | 6.6 |
| 3 | $2.5 \pm 0.2$ | 750 | 29.6 | 17.6 | 8.3 | 5.0 |
| 2 | $1.5 \pm 0.2$ | 430 | 19.8 | 11.7 | 5.5 | 3.3 |
| 1 | $0 \sim 0.9$ | 120 <br> or less <br> or | 14.8 | 8.8 | 4.2 | 2.5 |

※ When the mounting bracket with I/O terminal is mounted, adjust at a pot on the drive card.

PM500XE/XP

| Speed <br> Level | ※External <br> Voltage | ※external <br> Resistor $(\Omega)$ | Nominal <br> Speed <br> $100 \mathrm{~m} / \mathrm{min}$ | Nominal <br> Speed <br> $60 \mathrm{~m} / \mathrm{min}$ | Nominal <br> Speed <br> pom/min | Nominal <br> Speed <br> $17 \mathrm{~m} / \mathrm{min}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10 | $9.3 \sim 10$ <br> or <br> No input <br> voltage | 9.1 K or over <br> or <br> open | 104.0 | 61.7 | 29.2 | 17.4 |
| 9 | $8.5 \pm 0.2$ | 6.2 K | 95.4 | 56.6 | 26.8 | 15.9 |
| 8 | $7.5 \pm 0.2$ | 4.3 K | 78.0 | 46.3 | 21.9 | 13.0 |
| 7 | $6.5 \pm 0.2$ | 3.3 K | 69.4 | 41.2 | 19.5 | 11.6 |
| 6 | $5.5 \pm 0.2$ | 2.2 K | 60.7 | 36.0 | 17.0 | 10.1 |
| 5 | $4.5 \pm 0.2$ | 1.8 K | 52.0 | 30.9 | 14.6 | 8.7 |
| 4 | $3.5 \pm 0.2$ | 1.2 K | 34.7 | 20.6 | 9.7 | 5.8 |
| 3 | $2.5 \pm 0.2$ | 750 | 26.0 | 15.4 | 7.3 | 4.3 |
| 2 | $1.5 \pm 0.2$ | 430 | 17.3 | 10.3 | 4.9 | 2.9 |
| 1 | $0 \sim 0.9$ | 120 or less <br> or Short | 13.0 | 7.7 | 3.7 | 2.2 |

※ When the mounting bracket with I/O terminal is mounted, adjust at a pot on the drive card.

## PM605XE/XP

| Speed Level | ※External Voltage | ※External Resistor ( $\Omega$ ) | $\begin{aligned} & \hline \text { Nominal } \\ & \text { Speed } \\ & 100 \mathrm{~m} / \mathrm{min} \end{aligned}$ | Nominal Speed $60 \mathrm{~m} / \mathrm{min}$ | Nominal Speed <br> $30 \mathrm{~m} / \mathrm{min}$ | Nominal Speed <br> $17 \mathrm{~m} / \mathrm{min}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10 | 9.3~10 <br> No input voltage | $\begin{gathered} 9.1 \mathrm{~K} \text { or over } \\ \text { or } \\ \text { open } \end{gathered}$ | 125.9 | 74.7 | 35.4 | 21.0 |
| 9 | $8.5 \pm 0.2$ | 6.2 K | 115.4 | 68.5 | 32.4 | 19.3 |
| 8 | $7.5 \pm 0.2$ | 4.3K | 94.4 | 56.0 | 26.5 | 15.8 |
| 7 | $6.5 \pm 0.2$ | 3.3 K | 83.9 | 49.8 | 23.5 | 14.0 |
| 6 | $5.5 \pm 0.2$ | 2.2 K | 73.4 | 43.6 | 20.7 | 12.3 |
| 5 | $4.5 \pm 0.2$ | 1.8 K | 62.9 | 37.3 | 17.7 | 10.5 |
| 4 | $3.5 \pm 0.2$ | 1.2K | 42.0 | 24.9 | 11.8 | 7.0 |
| 3 | $2.5 \pm 0.2$ | 750 | 31.5 | 18.7 | 8.8 | 5.3 |
| 2 | $1.5 \pm 0.2$ | 430 | 21.0 | 12.4 | 5.9 | 3.5 |
| 1 | 0~0.9 | 120 or less or Short | 15.7 | 9.3 | 4.5 | 2.6 |

## Error output

- Thermal error/ Low voltage error/ EMF error
* Error output is not applicable for Dripproof option and 5 pin connector cable.


## Thermal error

- Error signal is discharged when thermal protector reacts at $95^{\circ} \mathrm{C}$ on the PCB inside of the motor
- Motor output goes down to $6.25 \%$ for cool down and runs at intermittent operation 0.5 s ON $/ 2 \mathrm{~s}$ OFF when thermal protector device reacts.
- Thermal error is automatically reset when temperature on circuit board becomes under $95^{\circ} \mathrm{C}$.



## Low voltage error

- Error signal is discharged and Power Moller stops when voltage drops down to 15 V or less continuously for 1 second.
- Low voltage error is automatically released when voltage raises 18 V or over continuously for 1 second.
caution) When voltage becomes under 8 V , Power Moller makes unexpected operation such as no error discharges.



## EMF error

- Error signal is discharged and Power Moller stops when motor voltage on a circuit board reaches 40 V due to generated EMF continuously for 2 seconds.
- EMF error is automatically reset when motor voltage becomes under 30 V continuously for 1 second.



## Operation

| Input voltage |  | DC24V( $\pm 10 \%$ ) |
| :---: | :---: | :---: |
| Starting current |  | XE series : $2.0 \pm 0.2 \mathrm{~A}$ XP series : $4.0 \pm 0.2 \mathrm{~A}$ |
| Maximum current |  | $10 \mathrm{~A} \leqq 1 \mathrm{msec}$ |
| Static current |  | 0.02A |
| Error output * |  | NPN open Colletor <br> Pulled up with $6.8 \mathrm{~K} \Omega$ resistor |
| Protection |  | Diode to protect from reverse polarity wiring 5A fuse |
| Insulation class |  | class E |
| Rated current (max. speed) |  | XE series: 1.7A XP series : 2.0A |
| Time delay |  | Initial reset : $\leqq 1 \mathrm{sec}$ |
| Reaction time to start motor |  | $\leqq 50 \mathrm{msec}$ |
| Thermal overload protection |  | reacts at $95^{\circ} \mathrm{C}$ (inside of the motor) |
| Brake |  | Electrical Brake (No retentivity) <br> 10 msec delay between stop signal and mechanical brake activation |
| Protection |  | IP50 (Dripproof type: IP54) |
| $\begin{aligned} & \hline \text { m } \\ & \vdots \\ & \vdots \\ & 0 \\ & 3 \\ & 3 \\ & \vdots \\ & \hline \end{aligned}$ | Ambient temperature | $0 \sim 40^{\circ} \mathrm{C}$ |
|  | Ambient humidity | $\leqq 90 \% \mathrm{RH}$ (no condensation) |
|  | Atmosphere | No coorrosive gas |
|  | Vibration | $\leqq 0.5 \mathrm{G}$ |

※ not applicable to the roller with M8 connector cable

Cable

Standard: with JST 7P connector

| Color | Description | Pin No. | Remarks |
| :--- | :--- | :---: | :---: |
| Red | +24 V | 1 | Housing <br> JST \# XHP-7 |
| Black | GND | 2 |  |
| Green | COMMON | 3 |  |
| White | RUN | 4 |  |
| Violet | DIR | 5 |  |
| Orange | External speed variation | 6 |  |
| Blue | ERROR | 7 |  |

NPN error signal internally pulled up with $6.8 \mathrm{~K} \Omega$ resistor.
for Dripproof / M8 connector cable

| Color | Description | Pin No. | Remarks |
| :--- | :--- | :---: | :---: |
| Brown | $+24 V$ | 1 | BRAD HARRISON |
| White | DIRECTION (PNP) | 2 |  |
| Blue | OV | 3 | equivalent to 405006P02M <br> (m** <br> (male) |
| Black | RUN (PNP) | 4 |  |
| Gray | SPEED VARIATION | 5 |  |

No.A-A80-G


- Sensor connector (CN2)

| Pin No. | Description | Connector | Suitable female connector |
| :---: | :---: | :---: | :---: |
| 1 | Power ( +24 V ) | $\begin{gathered} \text { Pin No. } \\ \begin{array}{\|ccc\|} \hline \vdots & 0 \\ \hline & 0 & 0 \\ 1 & 2 & 3 \\ \hline \end{array} \\ \text { JST-B3B-XH-A } \end{gathered}$ |  |
| 2 | Output |  | Contact <br> SXH-001T-P0. 6 <br> Wire |
| 3 | Power (0V < GND > ) |  | $0.08 \sim 0.3 \mathrm{~mm}^{2}$ <br> (AWG 28~22) |

- Control connector (CN3)

| Color | Description | Remarks |
| :--- | :--- | :--- |
| Brown | RUN / STOP | Connector : JST XHP-4 |
| Blue | Direction |  |
| Orange | Error output |  |
| Violet | Sensor output |  |

Error signal : NPN output, 24 V , pulled up with $4.7 \mathrm{k} \Omega$

- Power cable

| Color | Description | Connector No. |
| :--- | :---: | :--- |
| Red | +24 V | Cable tap $171404-1 \quad$ (AMP) <br> Black |
| Wire $: 1.25 \sim 2 \mathrm{~mm}{ }^{2} \quad$ (AWG 16~14) |  |  |

- LED

| LED1 (Green) | Illuminates with 24VDC Power |
| :--- | :--- |
| LED2 (Red) | Illuminates with error output / motor unplugged |

- VR1


Speed variation: 10 steps
Default setting: Max

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